**Group 6 Project Midterm Report**

**Project Title**: Driver drowsiness detection using deep learning

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1. **Motivation**

The primary motivation for choosing this topic is to apply deep learning concepts and techniques we learn in the class to a real-life problem with practical use.

Drowsiness is identified as one of the major causes of fatal traffic accidents. Unfortunately, about 20% of drivers tend to show drowsiness while driving, reported by National Safety Council[1]. This project aims to combine a fine-tuned neural network and a python-based face detection and feature extraction module into a real-time drowsiness detection system that will contribute to improving road safety.

Current state-of-the-art facial expression recognition models are able to achieve an accuracy of around 75-80%, utilizing the VGG-16 model [11]. Considering that drowsiness detection arguably easier to differentiate, we would consider an acceptable model performing with 70% validation accuracy and an accuracy greater than 75% being widely successful.

1. **Methodology**
   1. Dataset and data preprocessing

In this stage, we use a [kaggle dataset](https://www.kaggle.com/serenaraju/yawn-eye-dataset-new) that contains 2900 images with four labels, which are closed, open, no\_yawn, and yawn. Those four labels represent human face images with eyes closed, eyes open, without yawn, and with yawn, respectively. The four classes in the dataset are balanced.

In the next stage, we may add more image data to the dataset to improve accuracy. If time permits, we might also increase other labels to further categorize the spectrum between drowsy and non-drowsy.

* 1. Neural network architecture design

In the project proposal, we mentioned that we have reviewed some similar works[2][3] reporting good accuracy on ResNet, VGG-FaceNet[7], InceptionV3, AlexNet[6], FlowImageNet[8]. AlexNet is fine-tuned to learn features related to drowsiness. The VGG-FaceNet is trained to learn facial features related to drowsiness, which is robust to genders, ethnicity, hairstyle and various accessories adornment. FlowImageNet takes a dense optical flow image extracted from consecutive image sequences and is trained to learn behaviour features related to drowsiness, such as facial and head movements. The plan was to train multiple networks separately and ensemble good performing networks to cover all necessary features essential to detect drowsiness[4].

In this stage, we have implemented AlexNet. The result shows a possible overfitting and training time complexity performance is not well. Since other networks are likely to have even deeper architectures than AlexNet, they are likely to return an overfitting result as well.

We decided to build a less complex architecture until more suitable data is found and added on top of our current dataset. This network will also serve as the baseline for all other networks we are going to explore in the next stage. A summary of the baseline network is shown in Table 1.

A detailed description of hyperparameter tuning and the metrics are covered in section 3.

* 1. Face detection and feature extraction module

As pointed out by previous works[5], eye-based methods and mouth-based methods are the two main categories of drowsiness detection methods. We plan to cover both aspects by using multiple networks.

We plan to implement a python-based module to preprocess all images from the training set, validation set, and test set. This module will be used to perform facial recognition first, keep only the facial region of the image.

This module will also contain algorithms to extract eye regions and mouth regions separately. For the training set and validation set, either eye feature extraction or mouth region extraction functionality will be used to keep only the region that matches the label. For the test set, or real-time drowsiness detection test, we will use both functionalities to extract both eye and mouth region features and perform classification.

A scheme of this process can be found in Figure 1.

1. **Preliminary results**

Currently, the network with the best performance in accuracy and time complexity is the one with the architecture described in Table 1 (denoted as baseline model). The current CNN model has a total of 28,600 trainable parameters and is in the process of further development.

In this model, we use “categorical\_crossentropy” to define the loss function and use “accuracy” as the error metric. After 96 epoch, both accuracy and loss tend to flatten. Metrics at epoch 96:

test accuracy is 0.7875, test loss is 0.4176, training accuracy is 0.7931, training loss is 0.3992, validation accuracy is 0.7098, validation loss is 0.4812.

All things considered, Our model is showing promising signs and is performing at an acceptable level. We are hopeful that with more model parameter tuning that we will be able to achieve an even higher validation score.

A complete TensorBoard training history can be found in Figure 2 and Figure 3.

1. **Progress and future plans**

As stated in section 2.2, we have tried several deep architectures that all ended up giving overfitting results. Models with a greater number of layers, the ones with multiple dense connected layers, or the ones with too many parameters will take a relatively long time to train (from 3 minutes to 35 minutes per epoch).

After manipulating with parameters and models, we had the following findings:

Parameters that will not improve time complexity:

* batch\_size parameter of ImageDataGenerator,
* batch\_size parameter of the fit function,
* color\_mode (rgb or greyscale),
* with or without data augmentation,
* learning rate,
* training steps,
* validation steps.

Parameters that are relevant to time complexity:

* number of convolutional layers
* number of filters in each convolutional layer
* number of fully connected layers
* output parameters of dense layers
* if the number of parameters of any layer is too many

In the next stage, there are several items on our to-do list, including

1. adding more image data to our dataset by either find them from public sources or generating images by taking photos
2. implement deeper architectures if enough data is gathered to prevent overfitting
3. add more labels and more detailed categories
4. implement feature extraction modules to allow us to train or test based on certain regions of a facial image
5. implement real-time detection module and the underlying algorithm

Since item 5 is suspected to be out-of-scope of this course, we will only implement it if time permits. We are only adding this item to suit our interest as software engineering students, and we wish not to be held accountable for this item.

**Figures and Tables**

**Table 1. Baseline network summary**

**Table

Description automatically generated**

**Table 2. Project progress by midterm**

|  |  |
| --- | --- |
| **Task** | **Status** |
| Data Collection | Completed |
| Preprocessing and Data Augmentation | Completed |
| Build Model Architectures | Completed, more fine-tuning needed |
| Model Testing | Completed on existing networks |
| Final Report and Video Recording | Not started |

Video Input/Camera/Database

Face Detection

Eye/Mouth Region Extraction

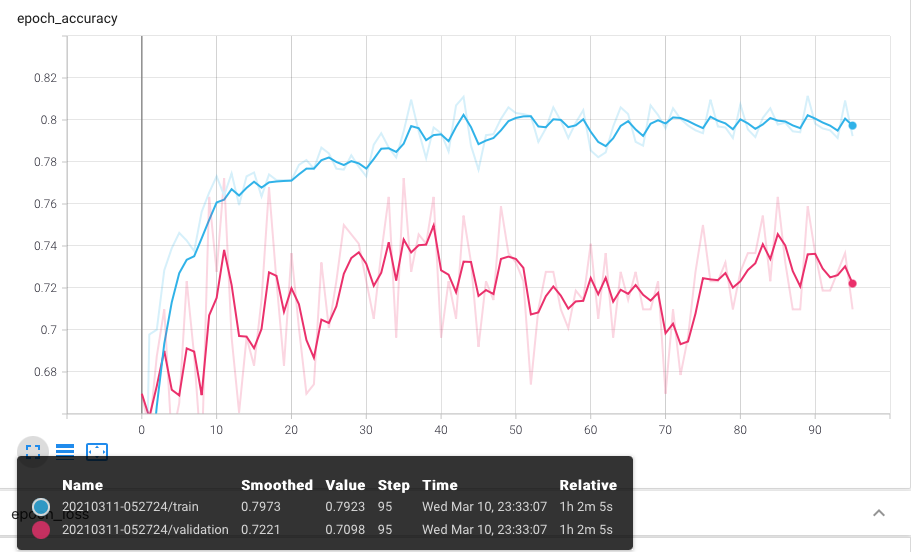
Feature Extraction

CNN Classifier

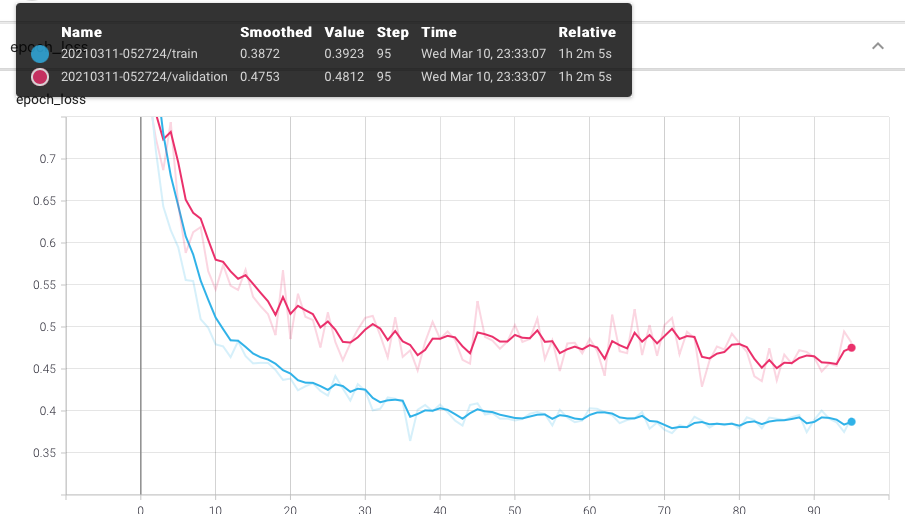
Drowsy

Non -Drowsy

**Figure 1. Proposed drowsiness detection process**

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**Figure 2. Baseline model training history, accuracy**

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**Figure 2. Baseline model training history, loss (categorical\_crossentropy)**

**References**

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**Member Contributions**

Each member had a different task and completed various sections of this proposal, and the workloads are distributed equally.